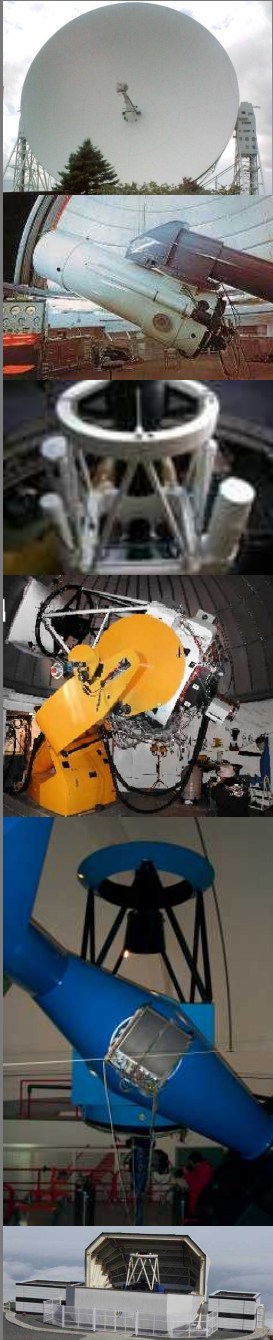


25 YEARS AFTER THE DISCOVERY: SOME CURRENT TOPICS ON LENSED QSOs

Santander (Spain), 15th-17th December 2004



# Transverse velocities of QSOs from microlensing parallax

Tyoma Tuntsov, Mark Walker and  
Geraint Lewis  
Sydney Uni

# Outline of the talk

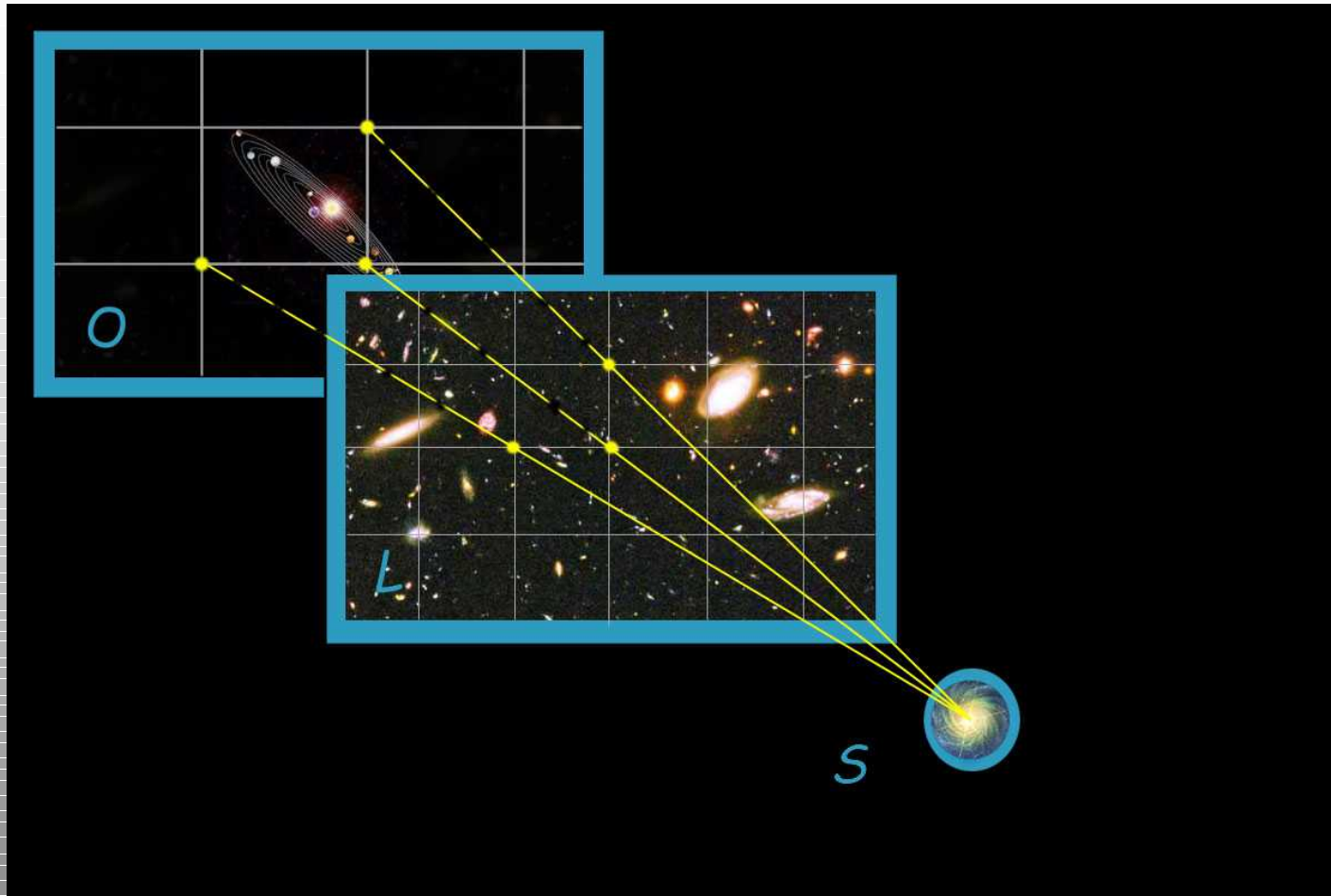
- What is the annual parallax effect?
- How can it be used to determine the transverse velocity in the system?
- Where can we find the effect?
- (Bad) Illustration – QSO2237+0305
- Conclusions and Outlook

# Outline of the talk

- **What is the annual parallax effect?**
  - Natural formalism for microlensing
  - What is the annual parallax effect?
  - What is it telling us?
- How can it be used to determine the transverse velocity in the system?
- Where can we find the effect?
- (Bad) Illustration – QSO2237+0305

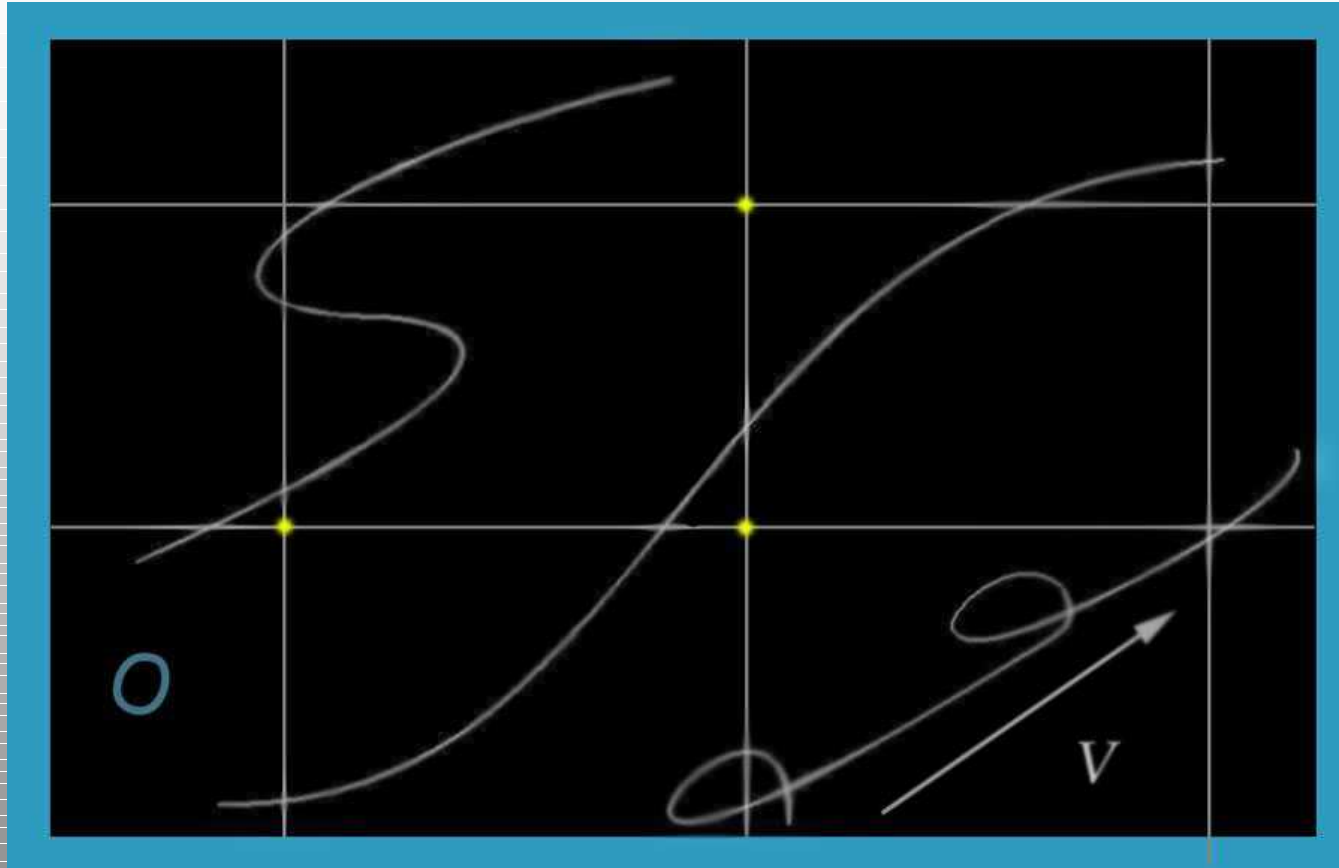
# Natural formalism for microlensing

(Gould, 2000, ApJ, 542, 785)



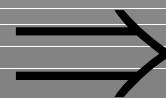
- All quantities projected onto observer plane
- Coordinate frame is fixed by source and lens
- Many things (those related to observer motion) look simpler!

# What is the annual parallax effect?



$$F = F_0(t - \tau) \times \mu(\mathbf{r}, t)$$

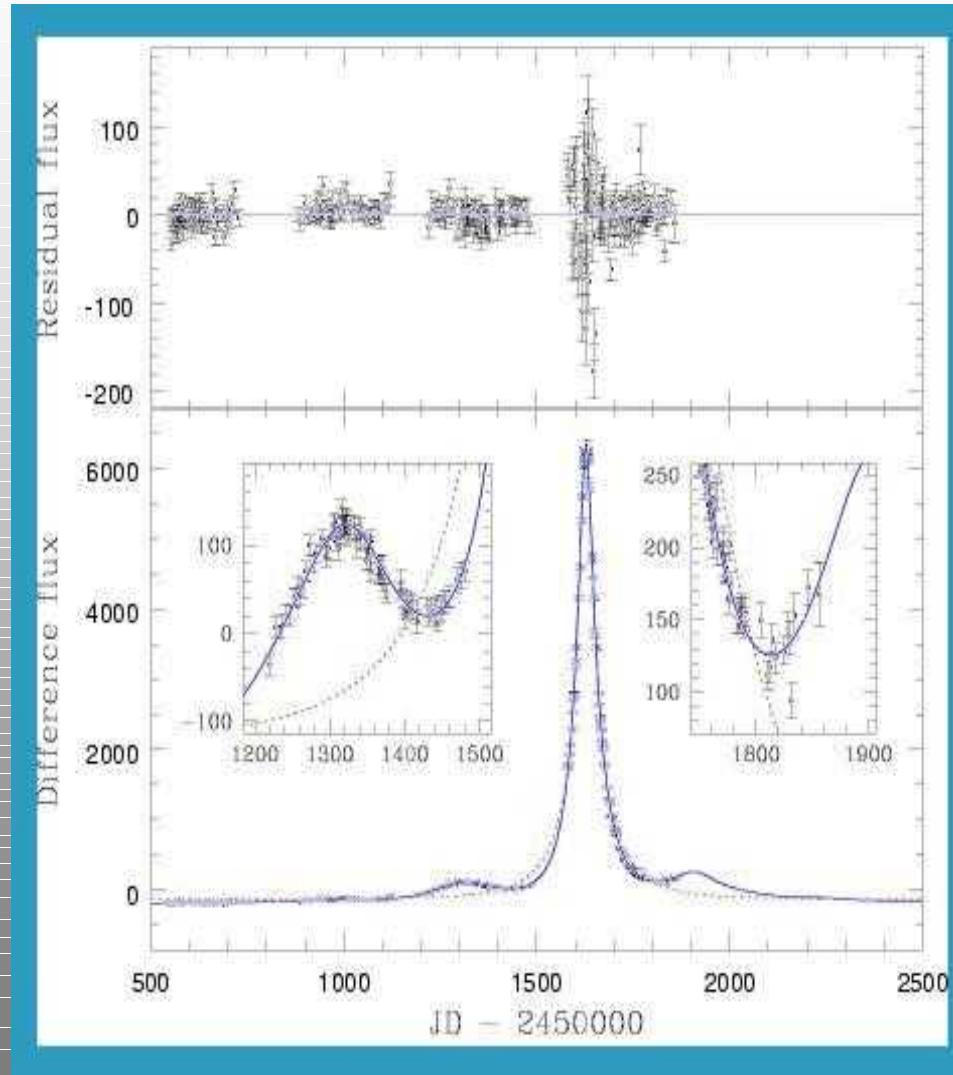
$$F_0 = \text{const}$$



$$m = m_0 + 2.5 \lg \mu(\mathbf{r}, t)$$

$$\mathbf{r}(t) = \mathbf{v} \cdot t + \mathbf{r}_e(t)$$

# What is it telling us?



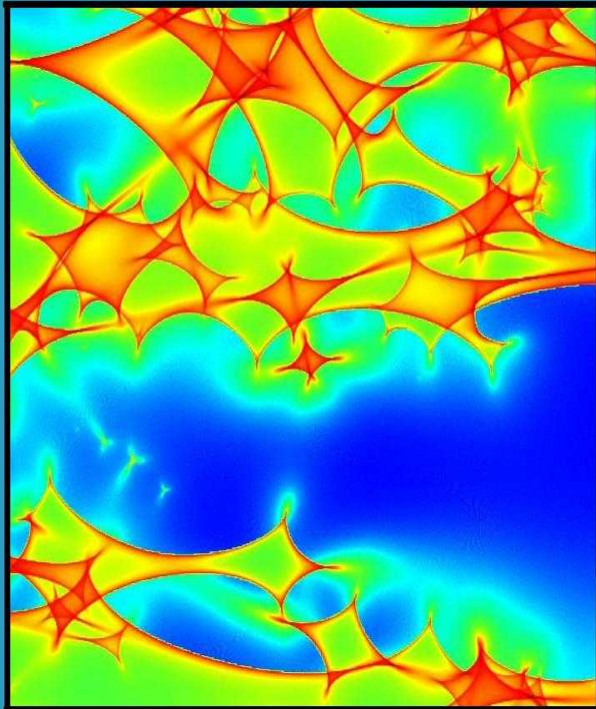
Galaxy: Optical depth  $\tau$  is low

$\Rightarrow$  Schwarzschild lens model for  $\mu(\mathbf{r}, t)$

$$\mu = \mu(\mathbf{r}) = \frac{y^2 + 2}{y\sqrt{y^2 + 4}}$$

$$y = \frac{|\mathbf{r}(t) - \mathbf{r}_0|}{r_E}$$

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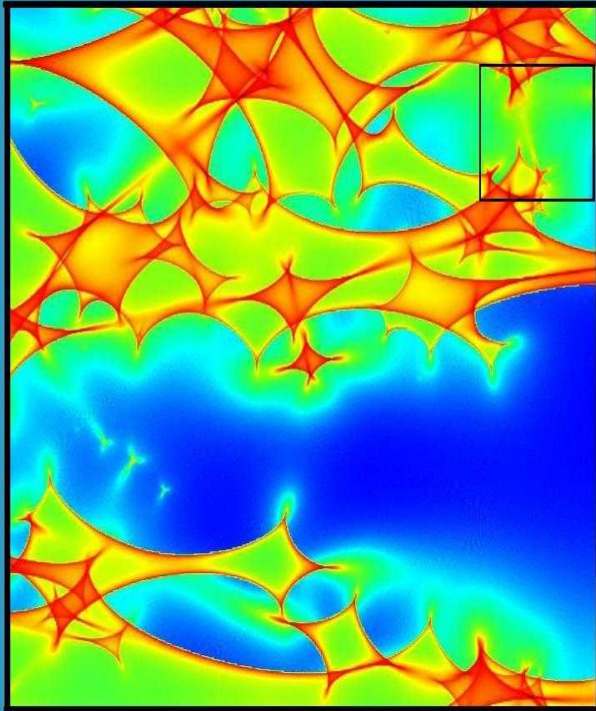
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 $\mu(\mathbf{r}, t)$  can be anything

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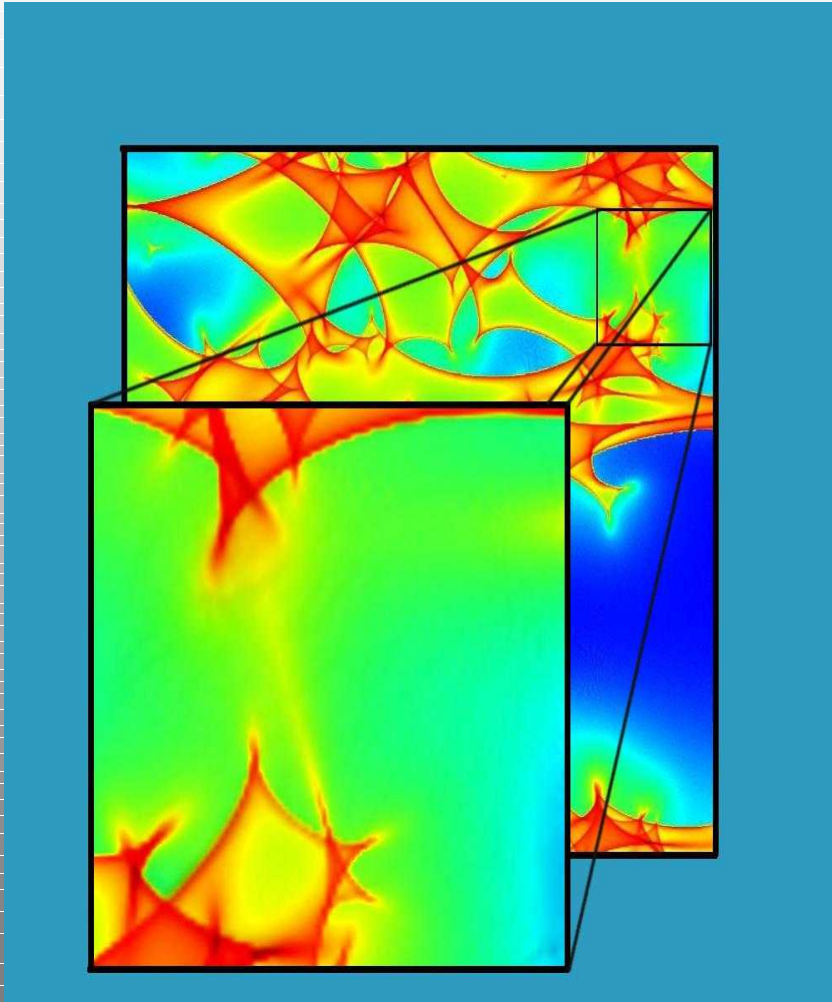
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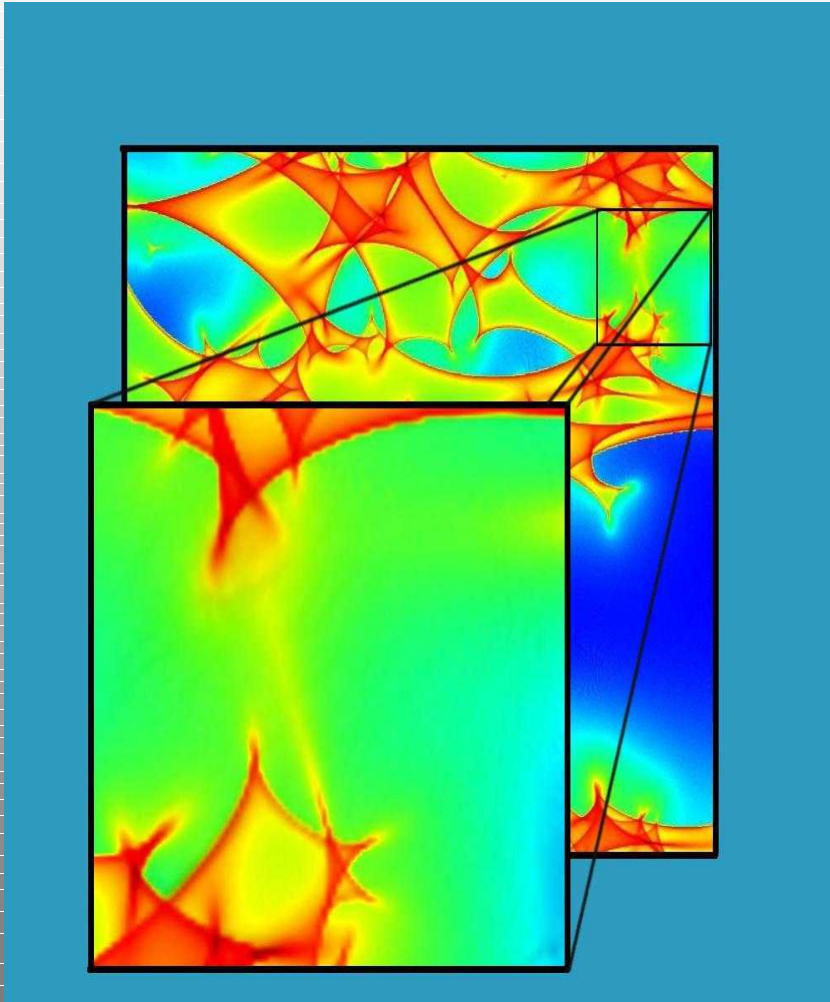
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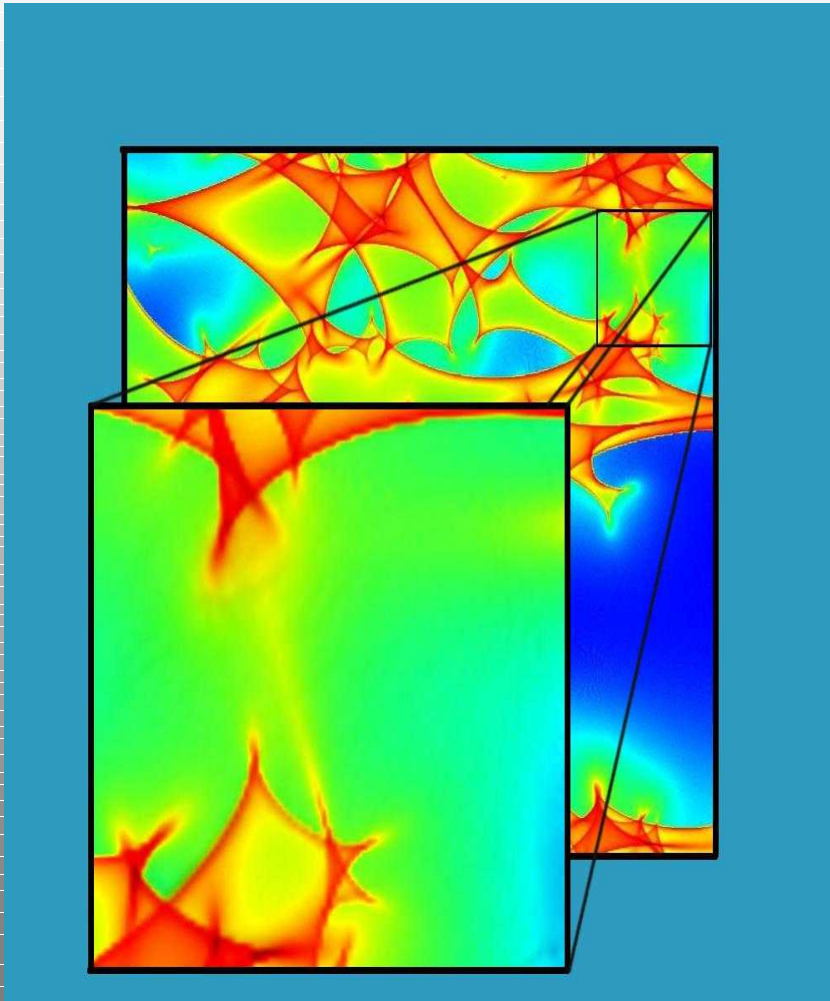
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- Microlensed QSOs:  $\tau \sim 1$   
 $\mu(\mathbf{r}, t)$  can be anything  
 $\Rightarrow$  Use Taylor expansion:

$$\mu(t) = \mu_0 + \frac{\partial \mu}{\partial t} (t - t_0) + (\mathbf{r}(t) - \mathbf{r}_0) \cdot \nabla \mu + \mathcal{R}$$

# What is it telling us?



$$m(t) = m_0 + \frac{\partial m}{\partial t}(t - t_0) + (\mathbf{r}(t) - \mathbf{r}_0) \cdot \nabla m + \mathcal{R}$$

$$\mathbf{r}(t) - \mathbf{r}_0 = \mathbf{v}t + \mathbf{r}_e(t) \quad \mathbf{r}_e = (x, y)$$

$$m_i - m_0 = T(t_i - t_0) \\ + X(x_i - x_0) + Y(y_i - y_0)$$

$$\nabla m = (X, Y)$$

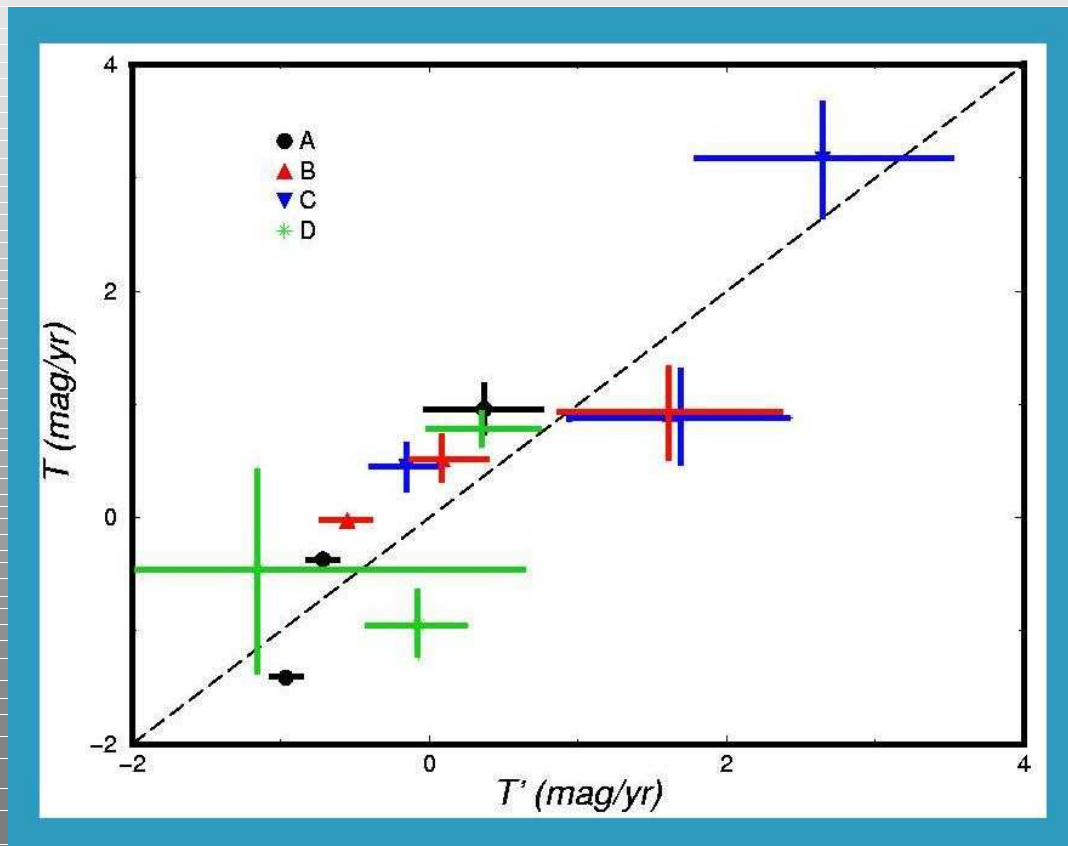
$$T = \frac{\partial m}{\partial t} + \mathbf{v} \cdot \nabla m$$

# Outline of the talk

- What is the annual parallax effect?
- **How can it be used to determine the transverse velocity in the system?**
  - Correlation between (T, X, Y) coefficients in different images
  - Individual velocities and magnification matrices
- Where can we find the effect?
- (Bad) Illustration – QSO2237+0305
- [Cribb et al. 2007](#)

# Correlations between (T, X, Y) coefficients in different images

$$m(t) = m_0 + \frac{\partial m}{\partial t}(t - t_0) + (\mathbf{r}(t) - \mathbf{r}_0) \cdot \nabla m + \mathcal{R}$$



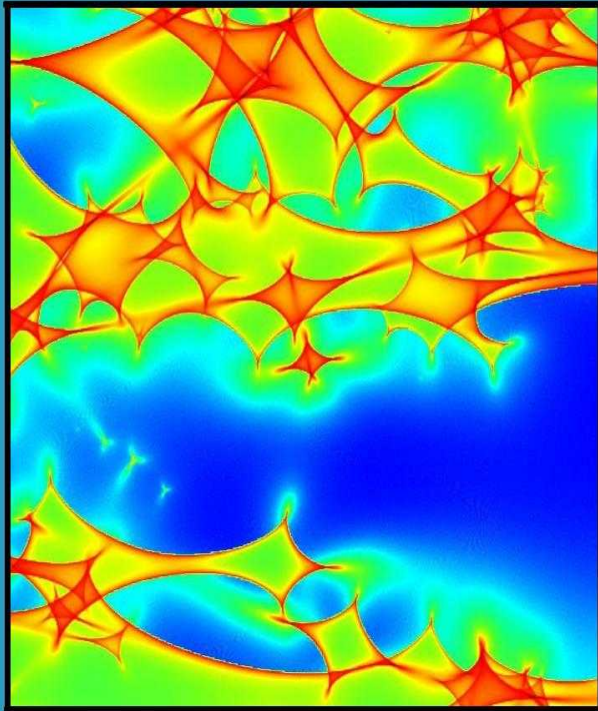
$$T = \frac{\partial m}{\partial t} + \mathbf{v} \cdot \nabla m$$

$$T'_j \approx \mathbf{v} \cdot \nabla m_j$$

$$T'_j \approx v_x X_j + v_y Y_j$$

Thus, at least three images required

# Individual velocities and magnification matrices



$$\mathbf{v}_j = \mathbf{v}_0 + \hat{\mathbf{A}}_j \mathbf{u}_j$$

- Assume  $|\hat{\mathbf{A}}_j \mathbf{u}_j| \ll \mathbf{v}_0$

$$(\mu_j = |\hat{\mathbf{A}}_j|^{-1})$$

**OR**

- Use independent regions of O-plane plus additional info

# Outline of the talk

- What is the annual parallax effect?
- How can it be used to determine the transverse velocity in the system?
- **Where can we find the effect?**
  - Order-of-magnitude argument
  - QSO wish list
- (Bad) Illustration – QSO2237+0305
- Conclusions and Outlook

# Order-of-magnitude argument

- How good is linear approximation?

$$m = m_0 + (\mathbf{v}t + \mathbf{r}_e) \cdot \nabla m + \mathfrak{R} + \Delta m \quad \mathfrak{R} = (\mathbf{v}t + \mathbf{r}_e)^2 D_2$$

- Rescaling to Einstein units:

$$m - m_0 = \frac{\mathbf{v}t + \mathbf{r}_e}{r_E} \cdot [r_E \nabla m] \\ + \left( \frac{\mathbf{v}t + \mathbf{r}_e}{r_E} \right)^2 [r_E^2 D_2] + \Delta m$$



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$$m - m_0 - \frac{\mathbf{v}t}{r_E} \cdot [r_E \nabla m] = \frac{\mathbf{r}_e}{r_E} \cdot [r_E \nabla m] + \left( \frac{\mathbf{v}t + \mathbf{r}_e}{r_E} \right)^2 [r_E^2 D_2] + \Delta m$$

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$$m - m_0 - \frac{\mathbf{v}t}{r_E} \cdot [r_E \nabla m] = \frac{\mathbf{r}_e}{r_E} \cdot [r_E \nabla m] \quad \leftarrow \text{Signal S}$$
$$+ \left( \frac{\mathbf{v}t + \mathbf{r}_e}{r_E} \right)^2 [r_E^2 D_2] + \Delta m$$

# Order-of-magnitude argument

- How good is linear approximation?

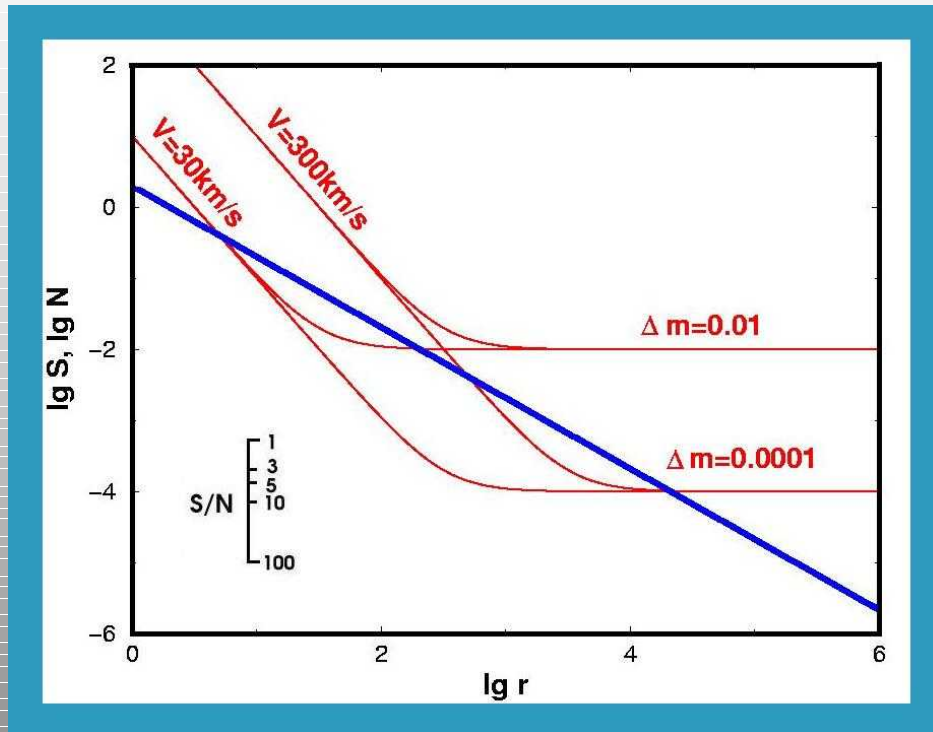
$$m = m_0 + (\mathbf{v}t + \mathbf{r}_e) \cdot \nabla m + \mathfrak{R} + \Delta m \quad \mathfrak{R} = (\mathbf{v}t + \mathbf{r}_e)^2 D_2$$

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$$m - m_0 - \frac{\mathbf{v}t}{r_E} \cdot [r_E \nabla m] = \frac{\mathbf{r}_e}{r_E} \cdot [r_E \nabla m] \quad \leftarrow \text{Signal } S$$

$$\text{Noise } N \quad \leftarrow + \left( \frac{\mathbf{v}t + \mathbf{r}_e}{r_E} \right)^2 [r_E^2 D_2] + \Delta m$$

# Order-of-magnitude argument



- $[r_E \nabla m] \sim 1$  ,  $[r_E^2 D_2] \sim 1$

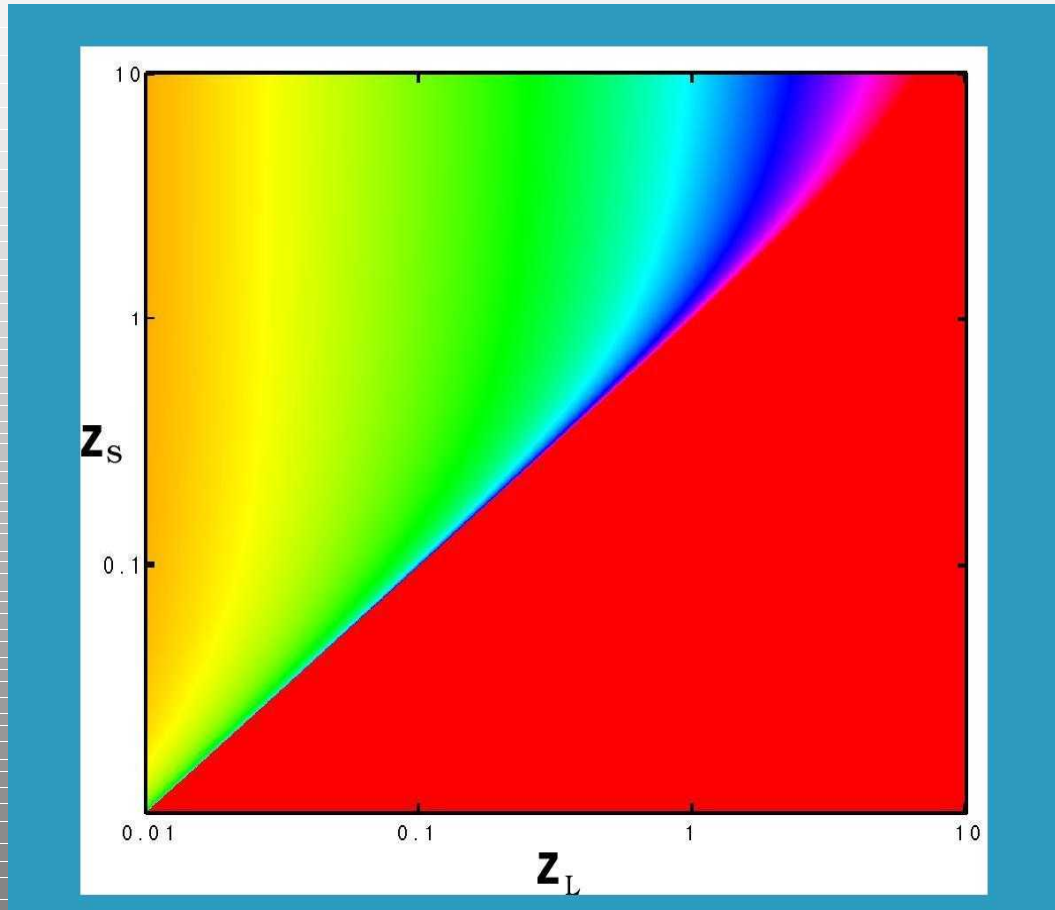
- $S = \frac{\mathbf{r}_e(t)}{r_E} \cdot [r_E \nabla m]$

– Optimal  $t \sim 1$  year

- $N \approx \left( \frac{\mathbf{v}t}{r_E} \right)^2 [r_E^2 D_2] + |\Delta m|$

$$S : N \approx \left( \frac{r_e}{r_E} \right) : \left( \left( \frac{\mathbf{v}t}{r_E} \right)^2 [r_E^2 D_2] + |\Delta m| \right)$$

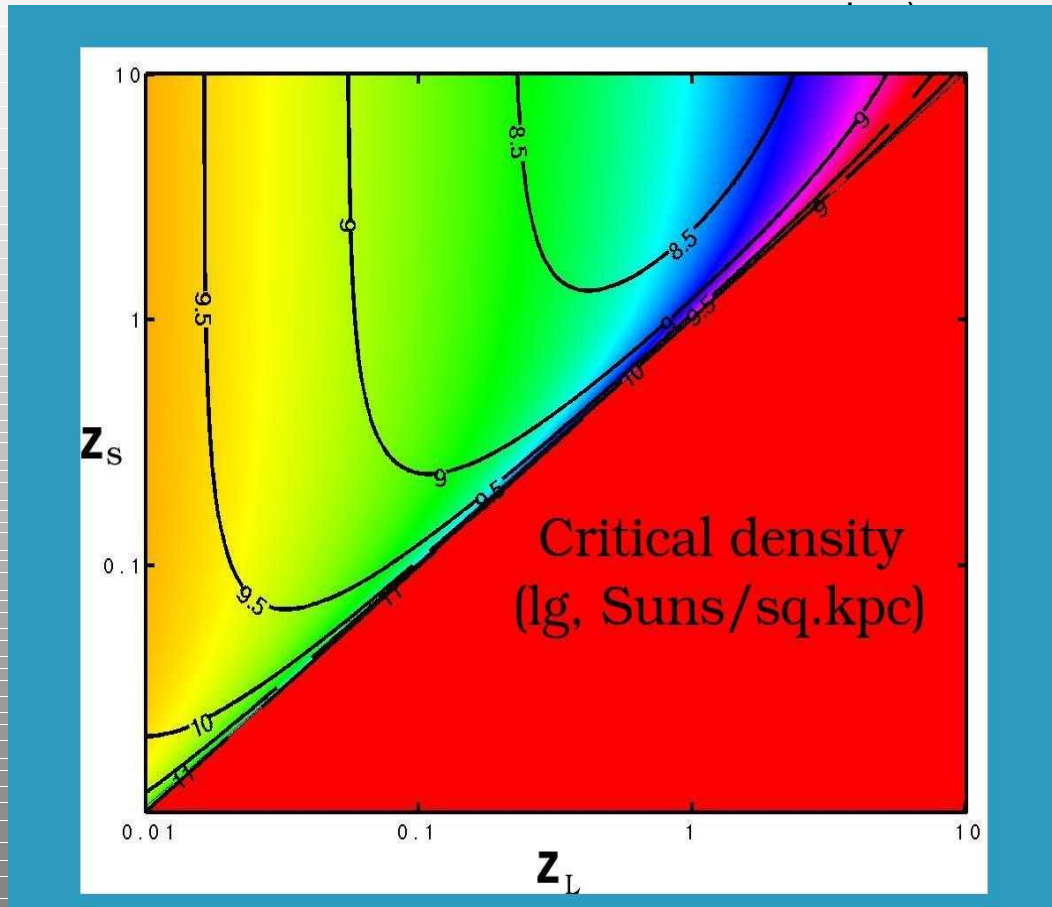
# Go Green



$$r_E = (1 + z_L) \sqrt{\frac{4GM}{c^2} \frac{D_L D_S}{D_{LS}}}$$

# Go Green

(if it

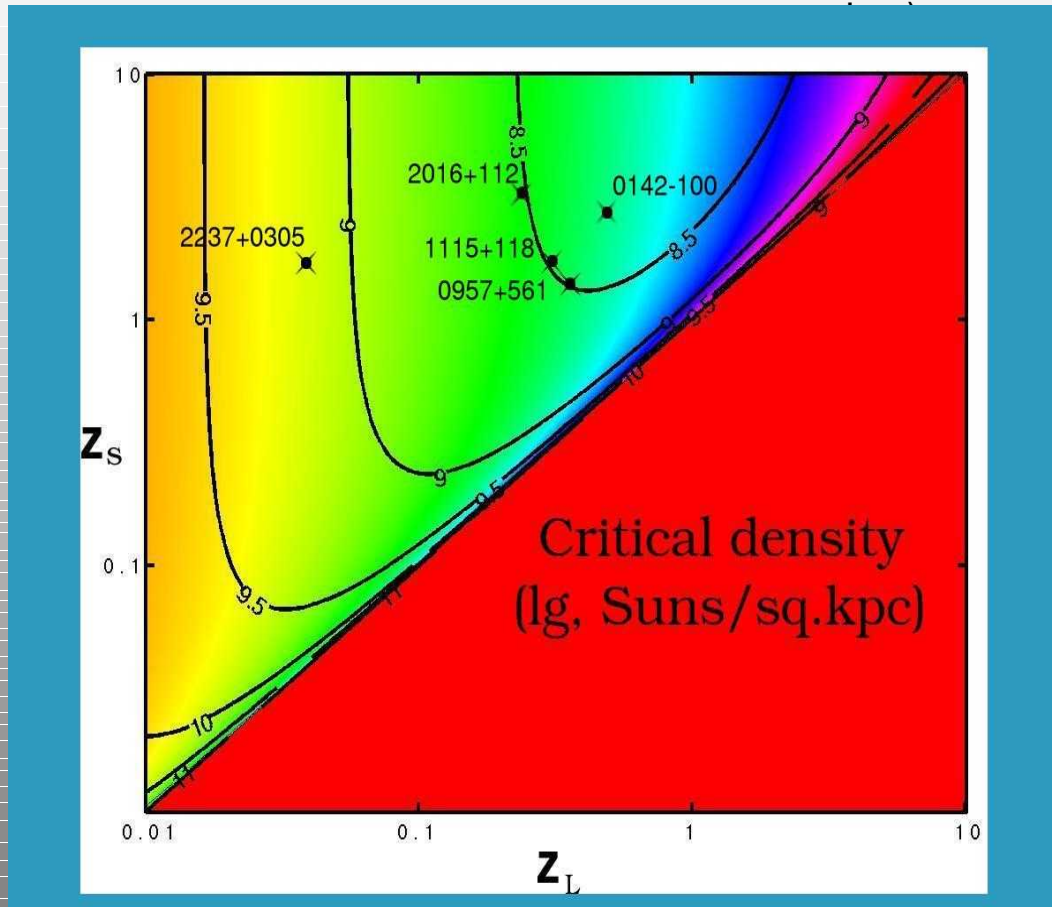


$$r_E = (1 + z_L) \sqrt{\frac{4GM}{c^2} \frac{D_L D_S}{D_{LS}}}$$

$$\Sigma_{cr} = (1 + z_L) \frac{c^2}{4\pi G} \frac{D_S}{D_L D_{LS}}$$

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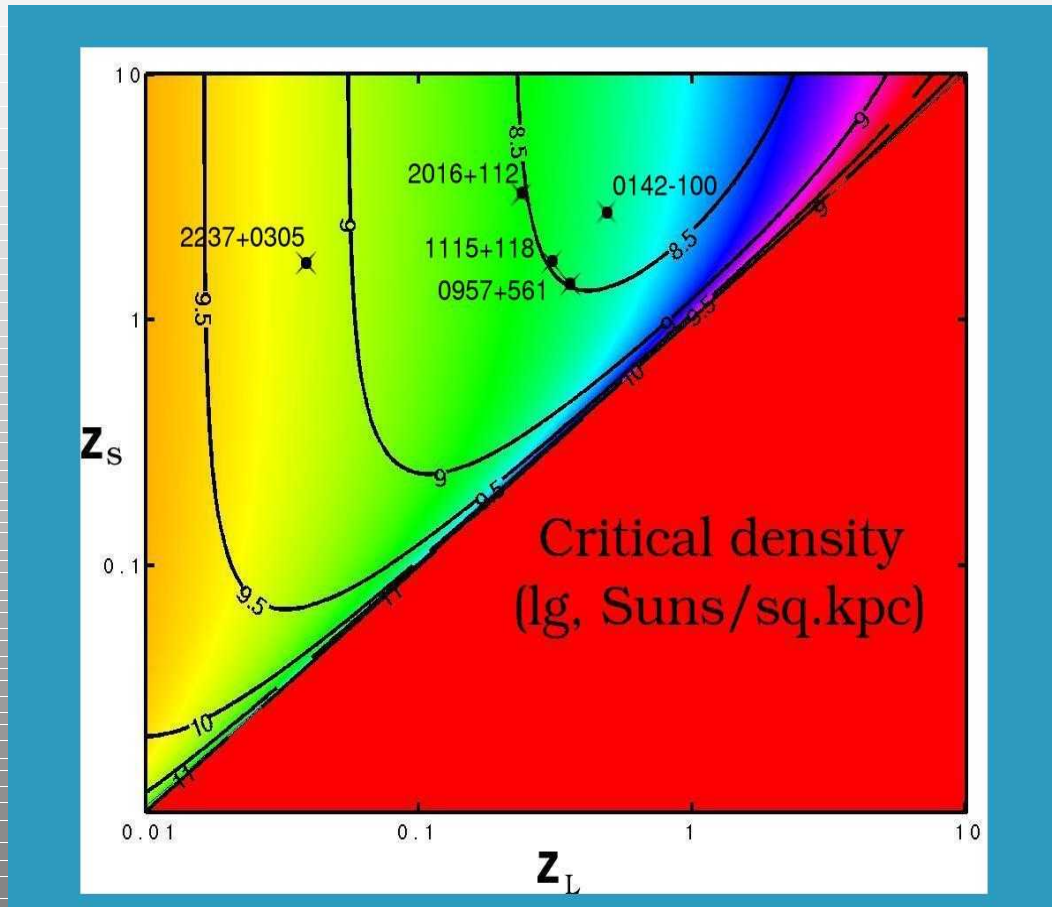
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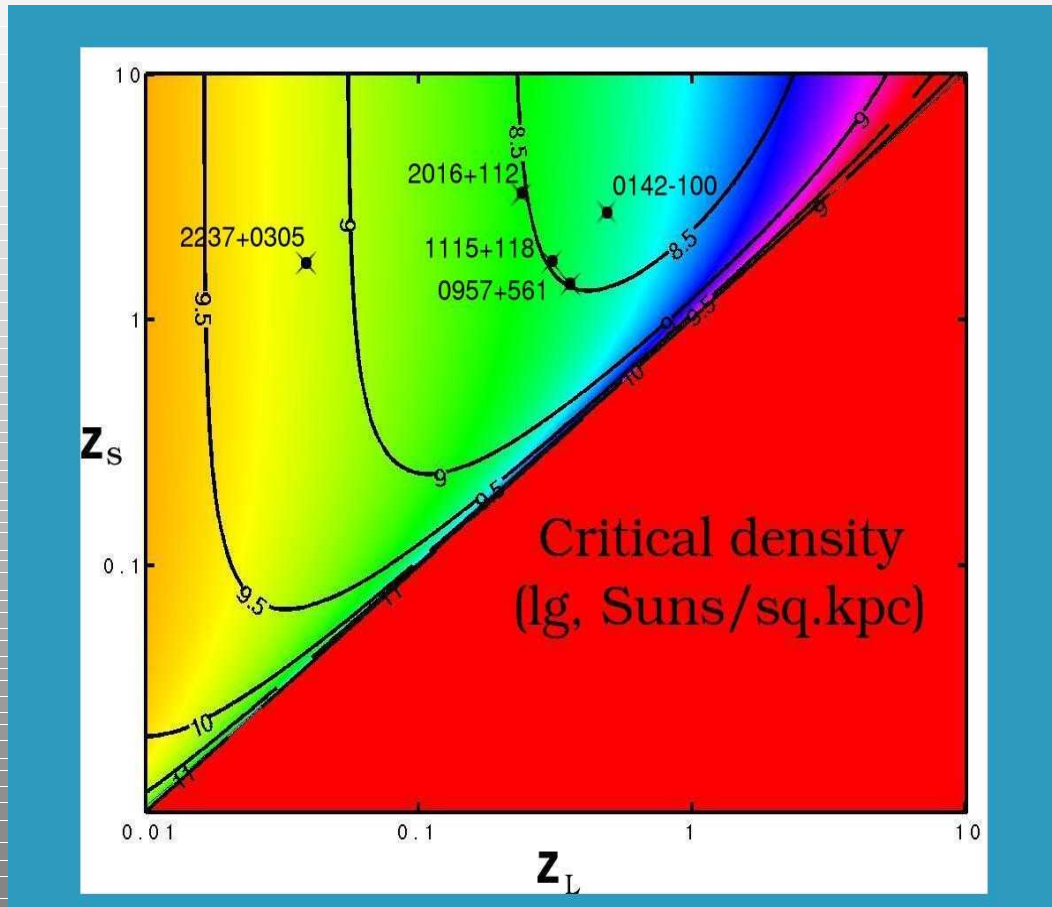
# QSO Wish List



- Redshifts of order unity

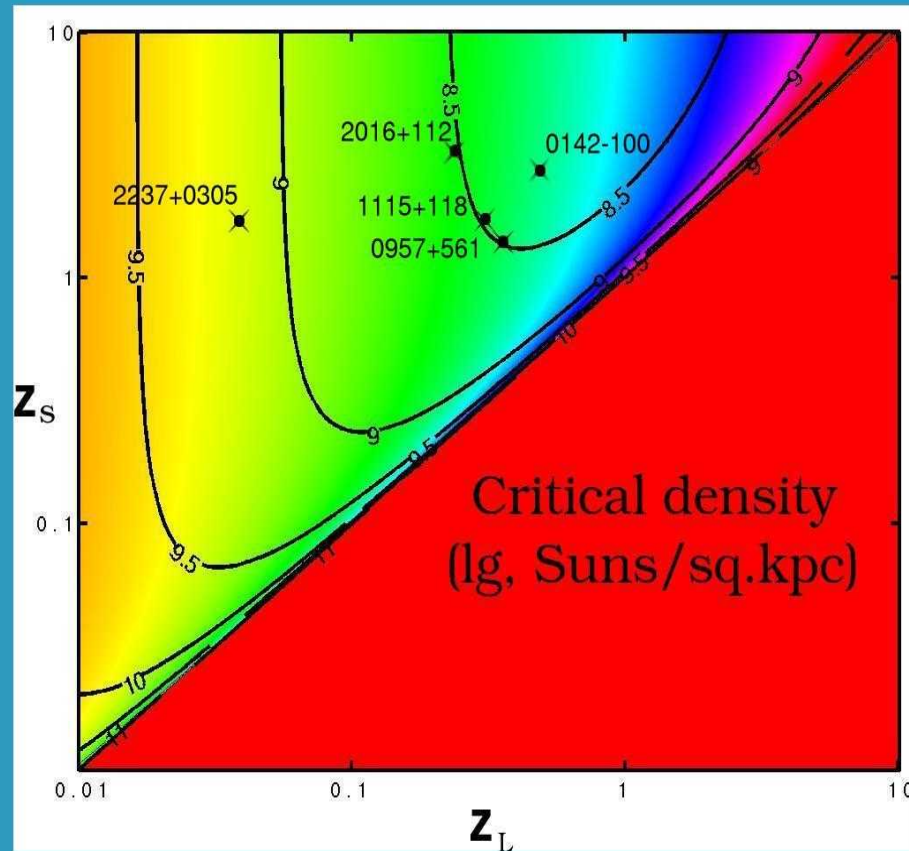


# QSO Wish List



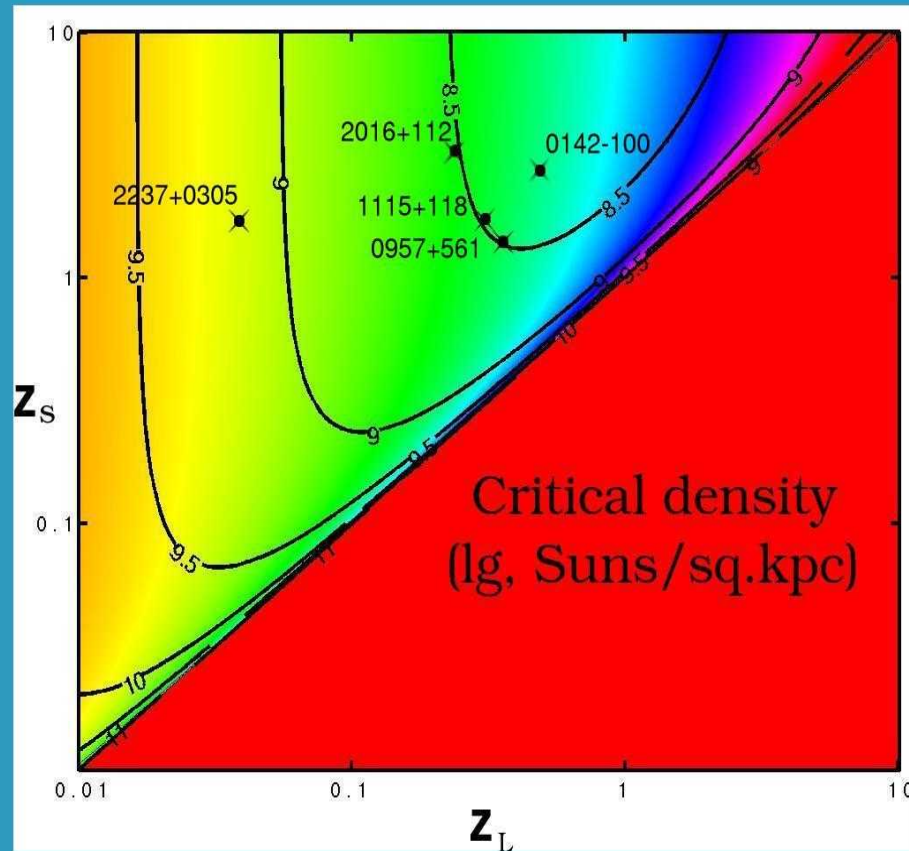
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  - Intrinsic variability constraint
  - bulk velocity constraints

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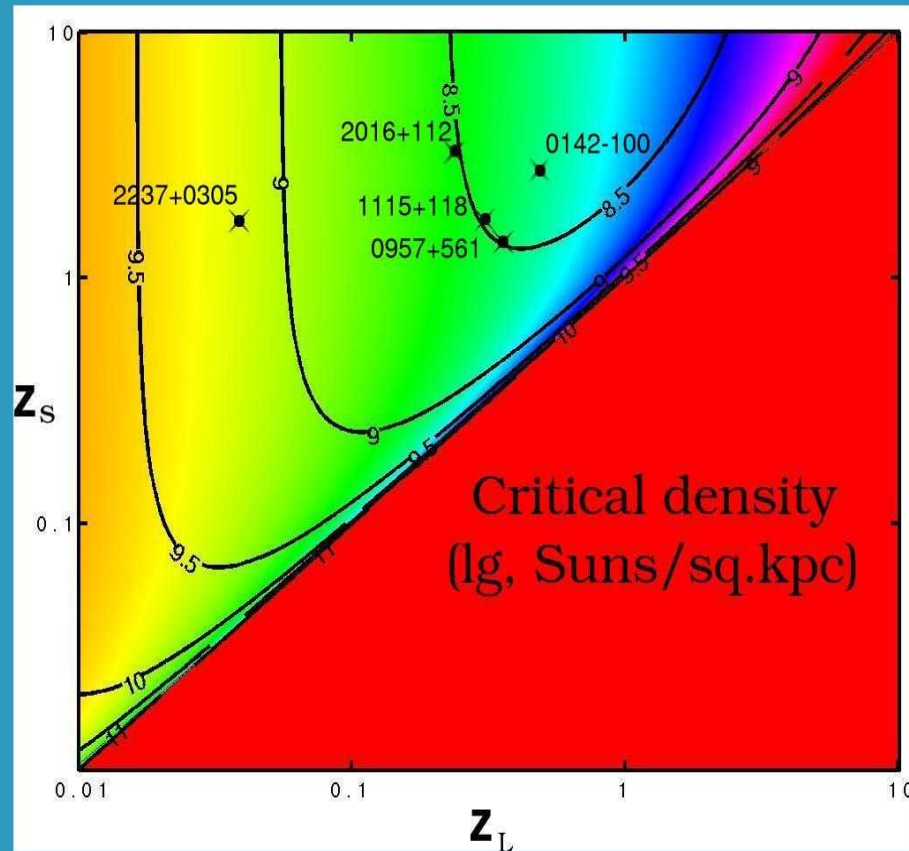
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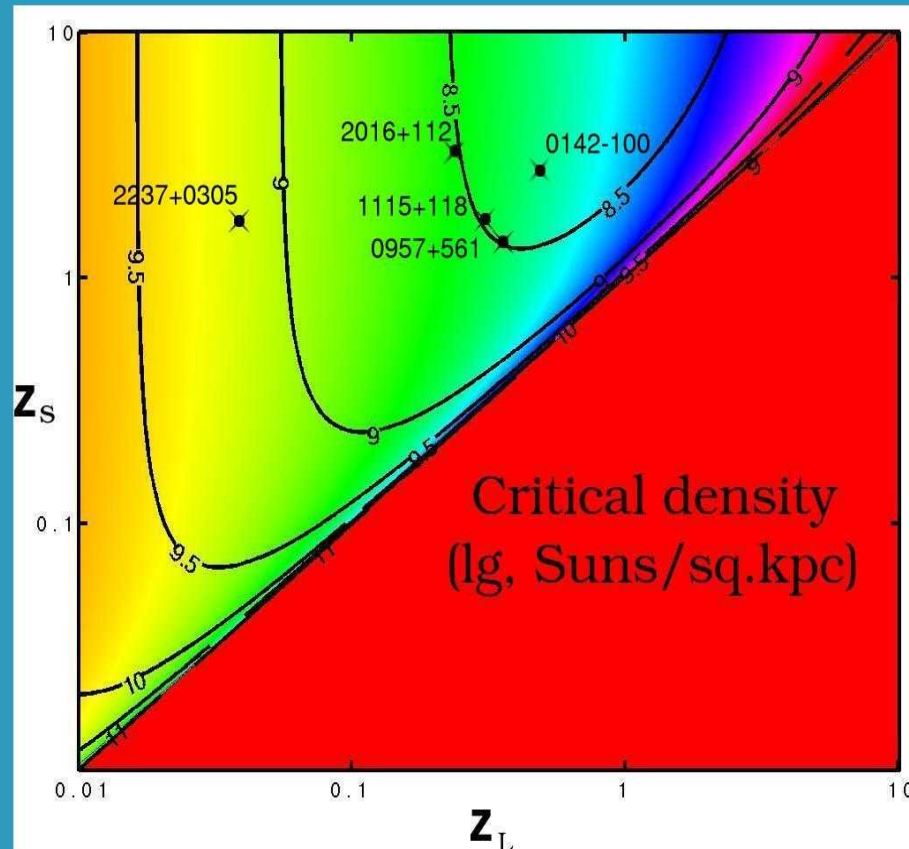
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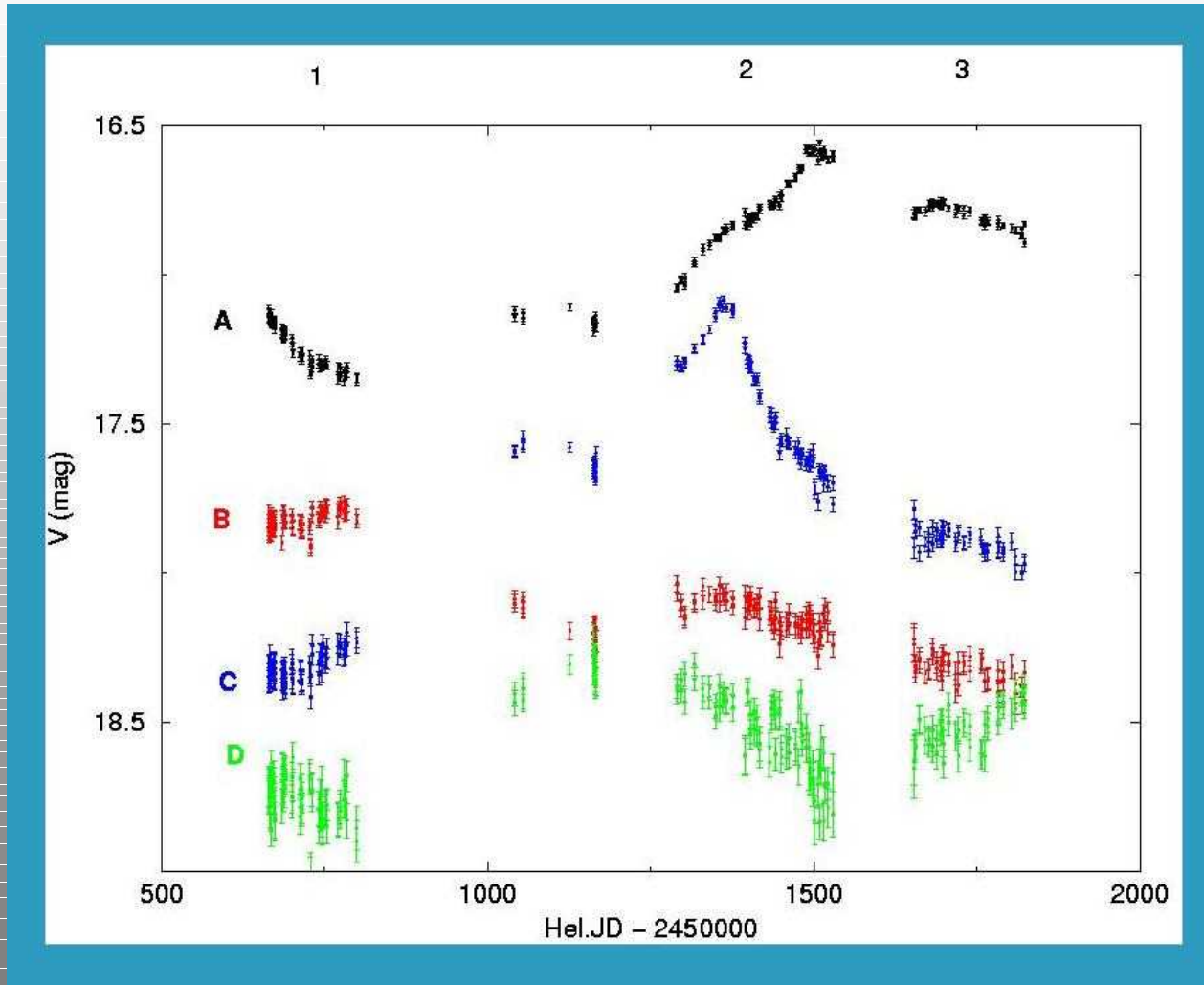
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And it should be bright, favourably located on the sky, year-around observable etc..

# Outline of the talk

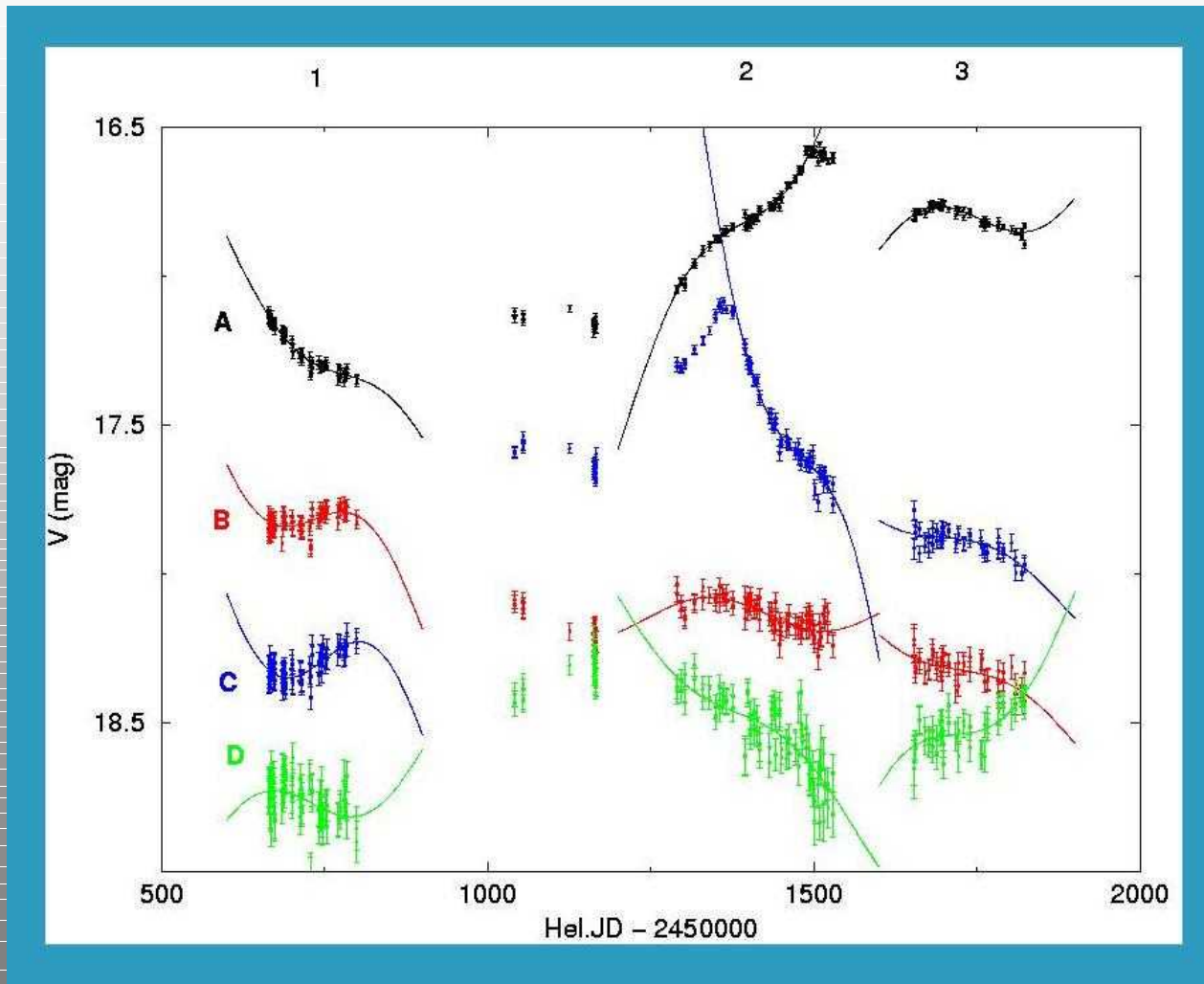
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# Application to QSO2237+0305



OGLE-II (Wozniak et al., 2000, ApJ, 529, 88)

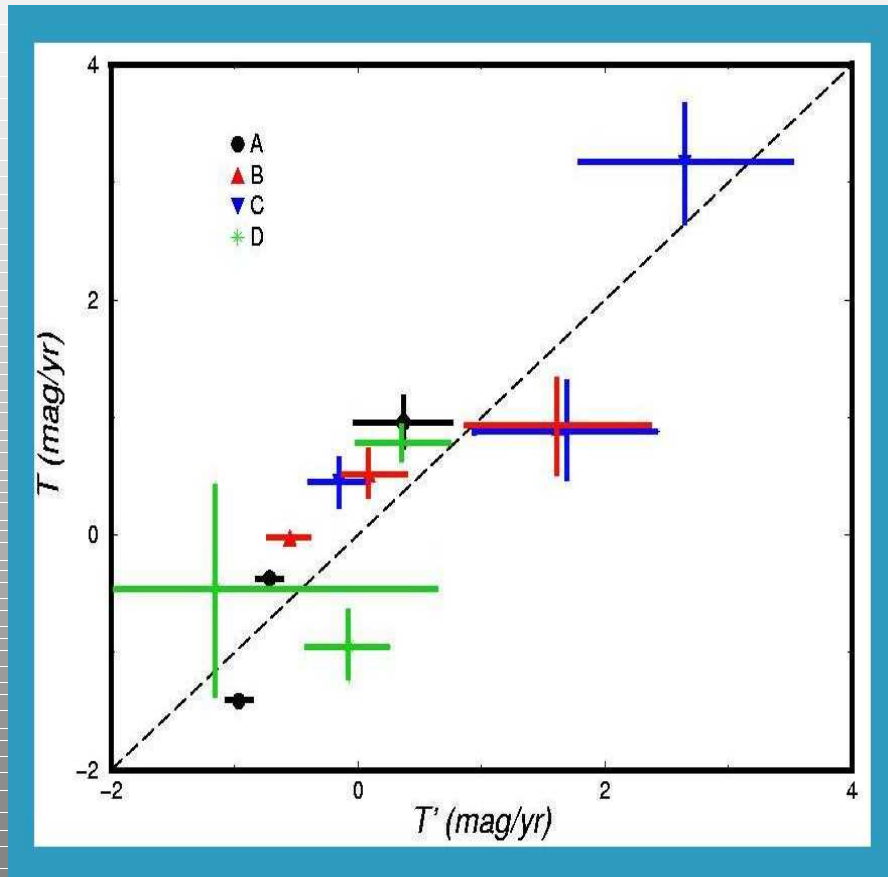
# Application to QSO2237+0305



OGLE-II (Wozniak et al., 2000, ApJ, 529, 88)



# Weird velocities



- Effective transverse velocity

$$\mathbf{v}_0 = (-15 \pm 7, -1 \pm 2) \text{ km/s}$$

$$\mathbf{v}_A = (5 \pm 20, 2 \pm 4) \text{ km/s}$$

$$\mathbf{v}_B = (-24 \pm 20, -4 \pm 6) \text{ km/s}$$

$$\mathbf{v}_C = (14 \pm 110, -7 \pm 20) \text{ km/s}$$

$$\mathbf{v}_D = (-20 \pm 4, -7 \pm 1) \text{ km/s}$$

- Using a different method

$$\mathbf{v}_0 = (-8 \pm 9, -2 \pm 2) \text{ km/s}$$

$$\mathbf{u}_A = (42 \pm 20, -4 \pm 5) \text{ km/s}$$

$$\mathbf{u}_B = (-49 \pm 17, -12 \pm 7) \text{ km/s}$$

$$\mathbf{u}_C = (20 \pm 40, -1 \pm 20) \text{ km/s}$$

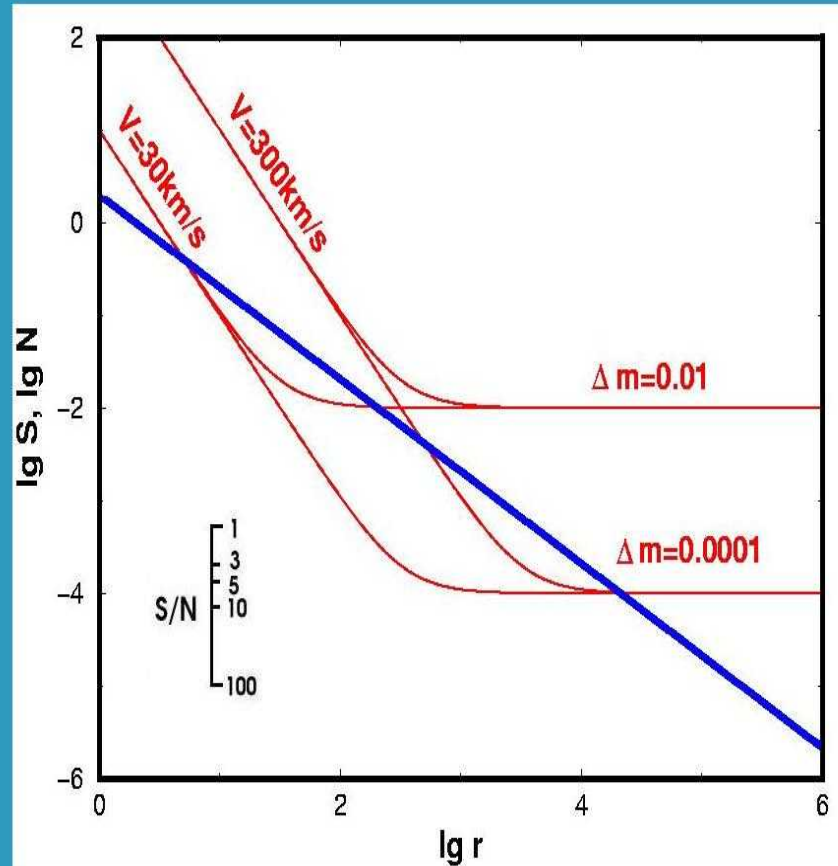
$$\mathbf{u}_D = (-13 \pm 5, 16 \pm 2) \text{ km/s}$$

(Schmidt, Webster & Lewis, 1998, MNRAS, 295, 488)

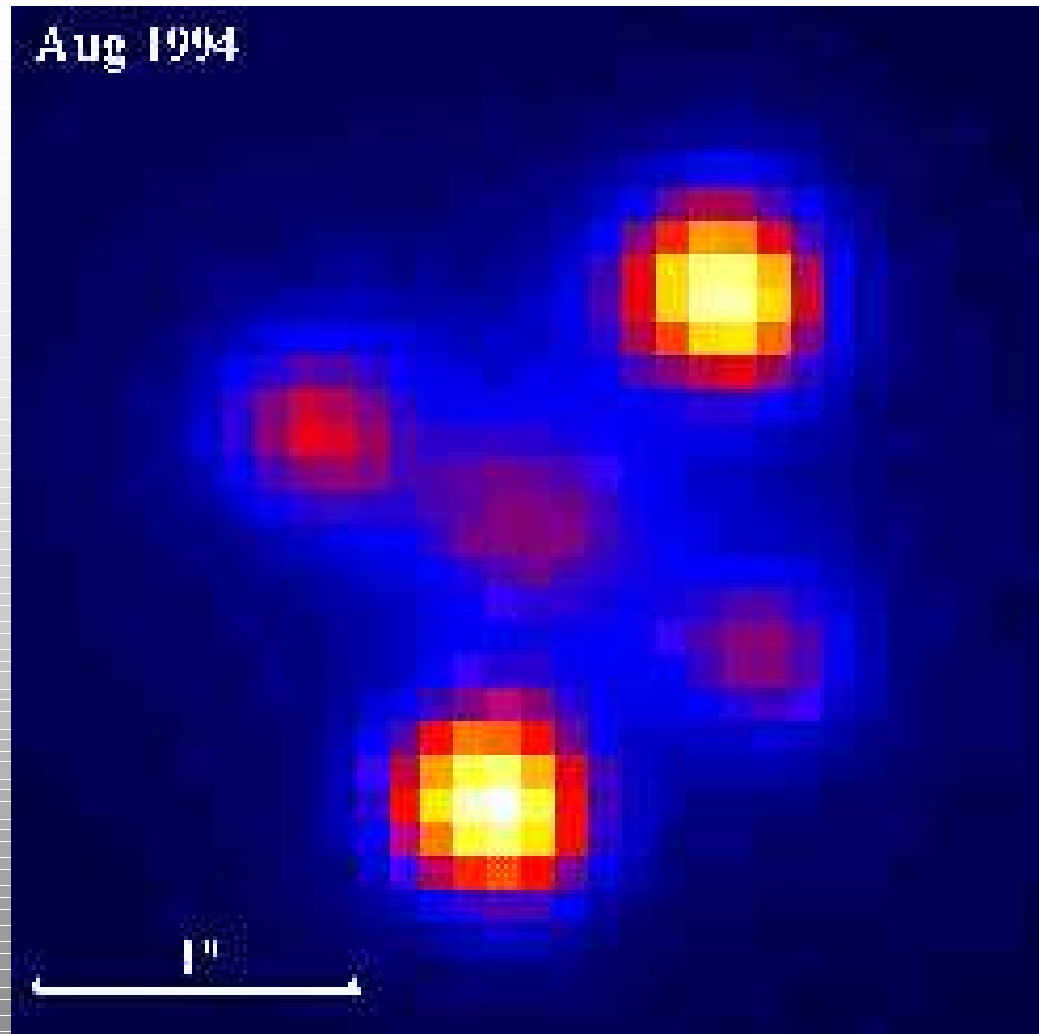
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# Conclusions and Outlook



- Photometric monitoring of some QSOs can help determine 3D picture of their motion
- Little chance to know *a priori* where the method will work
- Photometric accuracy is most important
- More data are needed
- Try it yourself!



Thank you for your attention!